

Robust Regression with Particle Swarm Optimisation and Differential Evolution

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1 Introduction

We provide a code example for a robust regression problem; for more details, please see Gilli et al. [2011]. (The vignette builds on the script `comparisonLMS.R`.)

2 Data and settings

We start by attaching the `NMOF` package and fixing a seed. We will use the function `lqs` from the `MASS` package [Venables and Ripley, 2002], so we attach that package as well.

```
> library("NMOF")
> library("MASS")
> set.seed(11223344)
```

We will use an artificial data set with n observations and p regressors, created with the function `createData`.

```
> createData <- function(n, p, constant = TRUE,
                        sigma = 2, oFrac = 0.1) {
  X <- array(rnorm(n * p), dim = c(n, p))
  if (constant)
    X[, 1L] <- 1L
  b <- rnorm(p)
  y <- X %%% b + rnorm(n)*0.5
  n0 <- ceiling(oFrac*n)
  when <- sample.int(n, n0)
  X[when, -1L] <- X[when, -1L] + rnorm(n0, sd = sigma)
  list(X = X, y = y, outliers = when)
}
```

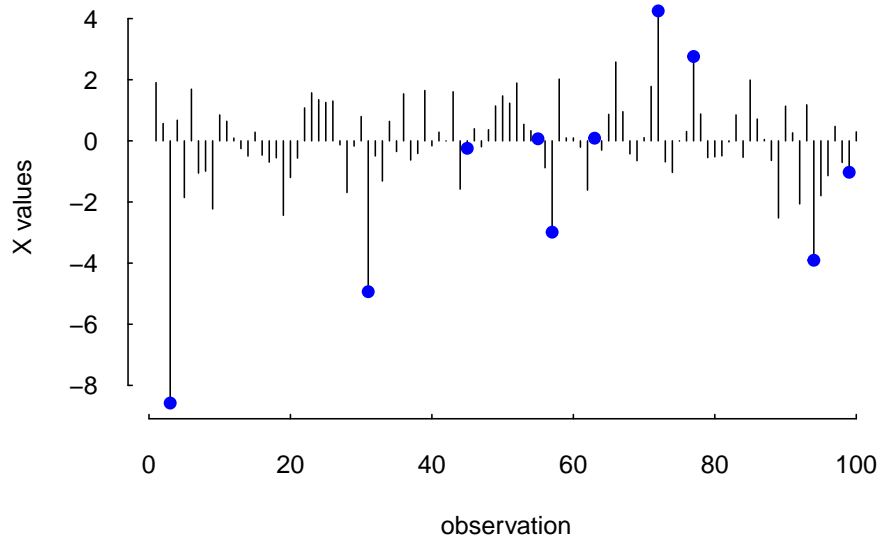
The function also takes arguments `constant` (logical: should the data-generating model contain a constant?); `sigma` (standard deviation of the outliers); and `oFrac` (fraction of outliers). The function evaluates to a list containing the regressors `X`, the regressand `y` and a list of the outliers.

We put `X` and `y` into the list `Data`. We also add the scalar `h`, which gives the order statistic of the squared residuals to be minimised. Note that we put `as.vector(y)` into `Data` so that the vector gets ‘recycled’ in the objective function.

```
> n <- 100L ## number of observations
> p <- 10L  ## number of regressors
> constant <- TRUE; sigma <- 5; oFrac <- 0.1
> h <- 75L  ## ... or use something like floor((n+1)/2)
> aux <- createData(n, p, constant, sigma, oFrac)
> X <- aux$X; y <- aux$y
> Data <- list(y = as.vector(y), X = X, h = h)
```

The outliers, added in blue, are often visible.

```
> par(bty = "n", las = 1, tck = 0.01, mar = c(4,4,1,1))
> plot(X[,2L], type = "h", ylab = "X values", xlab = "observation")
> lines(aux$outliers, X[aux$outliers,2L], type = "p", pch = 21,
       col = "blue", bg = "blue")
```



Two example objective functions, Least Trimmed Squares (LTS) and Least Quantile of Squares (LQS). Note that they are identical except for their last line.

```
> OF <- function(param, Data) {
  X <- Data$X; y <- Data$y
  aux <- y - X %*% param
  aux <- aux * aux
  aux <- apply(aux, 2L, sort, partial = Data$h)
  colSums(aux[1:Data$h, ]) ## LTS
}
> OF <- function(param, Data) {
  X <- Data$X; y <- Data$y
  aux <- y - X %*% param
  aux <- aux * aux
  aux <- apply(aux, 2L, sort, partial = Data$h)
  aux[Data$h, ] ## LQS
}
```

Both functions are vectorised. They work with a single solution (param would be a vector) or a whole population (param would be a matrix; each column would be one solution).

3 Using DE and PSO

We run DE and PSO. We compare the result with lqs.

```
> popsize <- 100L; generations <- 500L
> ps <- list(min = rep(-10,p),
  max = rep( 10,p),
  c1 = 0.9,
  c2 = 0.9,
  iner = 0.9,
  initV = 1,
  nP = popsize,
  nG = generations,
  maxV = 5,
  loopOF = FALSE,
  printBar = FALSE,
  printDetail = FALSE)
> de <- list(min = rep(-10,p),
  max = rep( 10,p),
  nP = popsize,
```

```

    nG = generations,
    F = 0.7,
    CR = 0.9,
    loopOF = FALSE,
    printBar = FALSE,
    printDetail = FALSE)
> system.time(solPS <- PSopt(OF = OF, algo = ps, Data = Data))

```

```

  user system elapsed
0.882  0.000  0.882

```

```

> system.time(solDE <- DEopt(OF = OF, algo = de, Data = Data))

```

```

  user system elapsed
0.906  0.000  0.906

```

```

> if (require("MASS", quietly = TRUE)) {
  system.time(test1 <- lqs(y ~ X[, -1L], adjust = TRUE,
    nsamp = 100000L, method = "lqs",
    quantile = h))
  res1 <- sort((y - X %*% as.matrix(coef(test1)))^2)[h]
} else
  res1 <- NA
> res2 <- sort((y - X %*% as.matrix(solPS$xbest))^2)[h]
> res3 <- sort((y - X %*% as.matrix(solDE$xbest))^2)[h]
> cat("lqs:   ", res1, "\n",
    "PSopt:  ", res2, "\n",
    "DEopt:  ", res3, "\n", sep = "")

```

```

lqs:   0.38106
PSopt: 0.29676
DEopt: 0.25894

```

To demonstrate the advantage of a vectorised objective function, we can compare it with looping over the solutions. We first set `loopOF` to `TRUE`, so we actually loop over the solutions. (We also reduce the number of objective function evaluations since we do not care about the actual solution, only about speed of computation.)

```

> popsize <- 100L; generations <- 20L
> de$nP <- popsize; de$nG <- generations
> ps$nP <- popsize; ps$nG <- generations
> de$loopOF <- TRUE; ps$loopOF <- TRUE
> t1ps <- system.time(solPS <- PSopt(OF = OF, algo = ps, Data = Data))
> t1de <- system.time(solDE <- DEopt(OF = OF, algo = de, Data = Data))

```

To evaluate the objective function in one step, we `loopOF` to `FALSE`.

```

> de$loopOF <- FALSE; ps$loopOF <- FALSE
> t2ps <- system.time(solPS <- PSopt(OF = OF, algo = ps, Data = Data))
> t2de <- system.time(solDE <- DEopt(OF = OF, algo = de, Data = Data))

```

Speedup:

```

> t1ps[[3L]]/t2ps[[3L]] ## PS

```

```

[1] 2.7778

```

```

> t1de[[3L]]/t2de[[3L]] ## DE

```

```

[1] 2.75

```

References

Manfred Gilli, Dietmar Maringer, and Enrico Schumann. *Numerical Methods and Optimization in Finance*. Elsevier/Academic Press, 2011. URL <http://enricoschumann.net/NMOF>.

William N. Venables and Brian D. Ripley. *Modern Applied Statistics with S*. Springer, 4th edition, 2002. URL <http://www.stats.ox.ac.uk/pub/MASS4>.